

REMARKS

This Preliminary Amendment cancels, without prejudice, claims 1-8 in the underlying PCT Application No. PCT/DE03/00463 and adds new claims 9-16. The new claims, inter alia, conform the claims to United States Patent and Trademark Office rules and does not add any new matter to the application.


In accordance with 37 C.F.R. § 1.125(b), the Substitute Specification (including the Abstract) contains no new matter). The amendments reflected in the Substitute Specification (including Abstract) are to conform the Specification and Abstract to United States Patent and Trademark Office rules or to correct informalities. As required by 37 C.F.R. §§ 1.121(b)(3)(ii) and 1.125(c), a Marked-Up Version of the Substitute Specification comparing the Specification of record and the Substitute Specification also accompanies this Preliminary Amendment. Approval and entry of the Substitute Specification (including Abstract) are respectfully requested.

The underlying PCT Application No. PCT/DE03/00449 includes an International Search Report, dated October 16 , 2003, a copy of which is included. The Search Report includes a list of documents that were considered by the Examiner in the underlying PCT application.

It is respectfully submitted that the subject matter of the present application is new, non-obvious, and useful. Prompt consideration and allowance of the application are respectfully requested.

Respectfully Submitted,

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RESTRAINT SYSTEM

5 ~~Background information~~

FIELD OF THE INVENTION

The present invention relates to a restraint system.

10 BACKGROUND INFORMATION

~~Restraint~~Conventional restraint systems ~~according to the related art~~ determine the deployment of restraining means via the acceleration which is measured on the transmission tunnel in the passenger compartment or in the exterior area of the vehicle, in the B-pillars for example, using peripheral sensors. Two acceleration sensors for each sensing direction are typically used to avoid erroneous deployment. The signals of both sensors are compared with one another and the deployment of restraining means, such as airbags for example, is ~~only~~ only permitted when both sensors measure a significant acceleration signal. Such a restraint system is ~~known from~~ described in German Patent Application No. DE 197 39 655 A1-655. A first acceleration-sensitive sensor is provided in this conventional restraint system, a first deployment criterion being derived from its output signal. A second deployment criterion is derived from the output signal of at least one additional sensor. At least two complex sensor systems are thus required to achieve a highly reliable performance of the restraint system and to prevent erroneous deployments in particular.

An accident sensor for triggering a motor vehicle safety system is ~~known from~~ described in German Patent Application No. DE 197 45 309 A1-309. This sensor includes deformable plastic parts which are mounted on the vehicle, as well as a microphone, in particular a structure-borne sound sensor. The deformation of the plastic parts generates a structure-borne sound that is measured in the frequency range of 60 Hz to 100 Hz.

SUMMARY

~~Advantages~~ In accordance with an example embodiment of the

5 ~~Invention~~ present invention, a substantially simpler and yet
~~reliable restraint system is—characterized by the features of~~
~~Claim 1. The present invention is built on the knowledge that,~~
in provided. In the event of an accident, high-frequency acoustic

10 signals are generated which may be converted into corresponding
electrical signals using an electroacoustic transducer and may
be analyzed as to whether an accident event is occurring.

Particularly advantageous is the use of an ultrasonic sensor as
the electroacoustic transducer, ~~since the applicant has found that~~
15 acoustic signals of high amplitude in the ultrasound range are
generated during accident events. An additional deployment
criterion for the deployment of restraining means may be derived
from these easily analyzable signals in a relatively simple manner.

~~Advantageous embodiments and refinements of the present invention~~
20 ~~arise from the subclaims.~~

Drawings

BRIEF DESCRIPTION OF THE DRAWINGS

25 The present invention is explained in greater detail below with
reference to the exemplary embodiments illustrated in the
drawing figures.

Figure 1 shows in a diagram the output signal of an ultrasonic
30 sensor as a function of time in an accident experiment.

Figure 2 shows a first exemplary embodiment of the present
invention in which an ultrasonic sensor is situated in the control
unit for sensing the passenger compartment.

35 Figure 3 shows a second exemplary embodiment in which an
ultrasonic sensor is situated in the airbag control unit.

and.

Figure 4 shows a third exemplary embodiment in which an ultrasonic sensor is also situated in the passenger compartment of the vehicle but outside of the airbag control unit.

~~Description of the Exemplary Embodiments~~

DETAILED DESCRIPTION OF EXAMPLE EMBODIMENTS

Figure 1 shows in a diagram the output signal of an electroacoustic transducer, in particular an ultrasonic sensor, as a function of time in an accident experiment. During the simulation of a very wide variety of vehicle accidents, the output signal of such an ultrasonic sensor US shows high amplitude values in a high frequency range of beyond approximately 50 kHz. In the diagram illustrated in Figure 1, the output signal of ultrasonic sensor US is detected starting at point in time $T=T_0$ as part of a crash experiment. The vehicle collides with a rigid barrier at a velocity of approximately 50 km/h at point in time $T=T_1$. As the diagram shows, the amplitude of the output signal of ultrasonic sensor US surges within a very short period of time, thereby representing a signal that may be analyzed comparatively simply. The generation of such ultrasonic signals is attributed to the deformation and breaking of vehicle parts during an accident.

An ultrasonic sensor US, situated in the passenger compartment of a vehicle, detects the ultrasonic signals in the vehicle in the event of an accident. In this instance, the ultrasonic sensor may be situated in the airbag control unit itself, or in another control unit, e.g., the control unit provided for sensing the passengers. As an external sensor, the ultrasonic sensor may alternatively be situated at almost any location within the passenger compartment of the vehicle. In the event that the ultrasonic sensor is installed in the airbag control unit itself, the measured signal is analyzed together with the signals of acceleration sensors which are also present there. In the event that the ultrasonic sensor is situated in a different control unit,

its output signal is transmitted to the airbag control unit and analyzed there. A particularly advantageous analysis of the output signal of the ultrasonic sensor may take place in such a way that the output signal is initially filtered in a low-pass filter and subsequently compared with a predefinable threshold value. If the threshold value is exceeded, this qualifies as a plausibility decision for the fact that an accident event is occurring. This plausibility decision is gated with the output signals of additional sensors of the restraint system. If the output signal of the ultrasonic sensor, as well as the output signals of the additional sensors of the restraint system conclude that an accident event is occurring, the deployment of restraining means such as airbags and seat-belt tensioners is enabled.

In further advantageous embodiments of the present invention, the output signal of the ultrasonic sensor may also be analyzed by using integration, window integration, bandpass filtering, or a combination of these measures.

A first exemplary embodiment of the present invention is explained with reference to Figure 2, in which ultrasonic sensor US is situated in control unit AOS for sensing the passenger compartment. Ultrasonic sensor US is connected to a first microprocessor MPI which is situated in control unit AOS. Control unit AOS for sensing the passenger compartment is connected to airbag control unit ACM. A second microprocessor MP2 and a first acceleration-sensitive sensor IAS of the restraint system are situated in airbag control unit ACM. A second acceleration-sensitive sensor PAS of the restraint system is connected to airbag control unit ACM. First sensor IAS is a sensor situated inside the vehicle, while second sensor PAS is situated externally. The output of control unit ACM is connected to a restraining means AB, such as an airbag in particular.

The first exemplary embodiment of the present invention operates as follows. In the event of an accident, acceleration-sensitive sensors IAS and PAS respond and each output a corresponding output

signal. In addition, ultrasonic sensor US, which is situated in control unit AOS for sensing the passengers, detects the high-frequency acoustic oscillations caused by the deformation or breaking of vehicle parts and converts these into a corresponding electrical output signal (Figure 1). High-frequency oscillations starting at approximately 50 kHz are preferably analyzed, since they are particularly characteristic of accident events. The output signal of ultrasonic sensor US is supplied to a low-pass filter (not shown in Figure 2) and analyzed there. The output signal, filtered in this way, is finally supplied to a threshold circuit and compared there with a predefinable threshold value S1. If the filtered output signal exceeds predefinable threshold value S1, it is assessed as a critical signal indicating an accident. If all three sensors, IAS, PAS, and US, deliver critical signals, i.e., signals which indicate an accident, everything suggests that an accident must plausibly be assumed and thus restraining means AB, such as, for example, airbags and/or seat-belt tensioners, must be deployed. This first exemplary embodiment according to Figure 2 is characterized in particular in that it has a very compact and space-saving design, since ultrasonic sensor US is situated in control unit AOS for sensing the passengers. This space-saving configuration makes particularly short electrical connections between ultrasonic sensor US and first microprocessor MP1 possible.

A second exemplary embodiment of the present invention is ~~explained~~described in connection with the aid of Figure 3. An airbag control unit ACM is illustrated there in the form of a block diagram. This airbag control unit ACM includes a first, internally situated acceleration sensor IAS and a microprocessor MP1. In addition, an external, acceleration-sensitive sensor PAS is connected to control unit ACM. An ultrasonic sensor US is situated directly in control unit ACM. In comparison with the first exemplary embodiment according to Figure 2, this results in an even more compact configuration having particularly short power connections between sensors IAS, US and microprocessor MP1 which is responsible for the analysis of the output signals of these

sensors.

A third exemplary embodiment of the present invention is explained with reference to Figure 4. An airbag control unit ACM is again illustrated, which includes an acceleration-sensitive sensor IAS and a microprocessor MP1. An externally situated acceleration sensor PAS is connected to control unit ACM. In addition, an ultrasonic sensor US is provided which is, however, situated outside control unit ACM and connected to it via a line. This exemplary embodiment of the present invention mentioned last is not as compact as the exemplary embodiments of the present invention explained above with reference to Figures 2 and 3. However, a great advantage lies in the fact that in this exemplary embodiment, from the configurational point of view, the ultrasonic sensor may be mounted in an optimal location, independently of control units ACM or AOS. This exemplary embodiment is thus particularly flexible.

It is generally known that an impact on the vehicle body, falling rocks for example, or driving over a pothole, generates acoustic oscillations. However, such oscillations subside again relatively quickly. In order to reliably prevent an erroneous deployment of restraining means in the presence of such innocuous acoustic oscillations, a time threshold is additionally provided in an advantageous further embodiment of the present invention. This means that threshold value S1 must be exceeded at least during a time interval ΔT before the ultrasonic signal is considered to be critical.

~~Abstract~~

ABSTRACT

A restraint system ~~is described~~ which, in addition to at least
5 one acceleration-sensitive sensor ~~IAS, PAS~~, includes at least one
ultrasonic sensor ~~US~~ which analyzes ultrasonic signals which occur
in the event of an accident.

~~(Figure 2)~~ _____

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